VECTOR AND AFFINOR FIELDS ON CROSS-SECTIONS IN THE SEMI-COTANGENT BUNDLE

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Abstract. The main purpose of this paper is to study the behavior of complete lifts of vector and affinor (tensor of type (1,1)) fields on cross-sections for pull-back (semi-cotangent) bundle t*B.

1. Introduction

Let an *n*-dimensional differentiable manifold M_n of class C^{∞} is a fiber bundle (M_n, π_1, B_m) with projection $\pi_1 : M_n \to B_m$. We use the notation $(x^i) = (x^a, x^\alpha)$, where the indices i, j, \ldots run from 1 to n, the indices a, b, \ldots from 1 to n - m and the indices α, β, \ldots from n - m + 1 to n, x^{α} are coordinates in B_m, x^a are fibre coordinates of the bundle $\pi_1 : M_n \to B_m$.

Let $(T^*(B_m), \tilde{\pi}, B_m)$ be a cotangent bundle with base space B_m . Then the semi-cotangent [9], [10] bundle (induced or pull-back) of $(T^*(B_m), \tilde{\pi}, B_m)$ is the bundle $(t^*(B_m), \pi_2, M_n)$ over M_n with a total space

$$t^{*}(B_{m}) = \{ ((x^{a}, x^{\alpha}), x^{\overline{\alpha}}) \in M_{n} \times T^{*}_{x}(B_{m}) : \pi_{1}(x^{a}, x^{\alpha}) = \widetilde{\pi}(x^{\alpha}, x^{\overline{\alpha}}) = (x^{\alpha}) \} \\ \subset M_{n} \times T^{*}_{x}(B_{m})$$

and with the projection map $\pi_2 : t^*(B_m) \to M_n$ defined by $\pi_2(x^a, x^\alpha, x^{\overline{\alpha}}) = (x^a, x^\alpha)$, where $T^*_x(B_m)(x = \pi_1(\widetilde{x}), \widetilde{x} = (x^a, x^\alpha) \in M_n)$ is the cotangent space at a point x of B_m (for definition of the pull-back bundle, see for example [1], [3], [5], [6]), where $x^{\overline{\alpha}} = p_\alpha(\overline{\alpha}, \overline{\beta}, ... = n+1, ..., m)$ are fiber coordinates of cotangent bundle $T^*(B_m)$. We denote by $\mathfrak{S}^p_q(M_n)$ and $\mathfrak{S}^p_q(B_m)$ the modules over $F(M_n)$ and $F(B_m)$ of all tensor fields of type (p,q) on M_n and B_m , respectively, where $F(M_n)$ and $F(B_m)$ denote the rings of real-valued C^{∞} -functions on M_n and B_m , respectively.

If $\pi_1 : M_n \to B_m$ is a differentiable map between the manifolds M_n and B_m then the functions on B_m can be pulled back by π_1 to give functions on M_n . β_{θ} is differentiable as a mapping $M_n \to t^*(B_m)$ if and only if $\Phi \in C^{\infty}(B_m)$ implies $\beta_{\theta}(\Phi) \in C^{\infty}(M_n)$, where $(\beta_{\theta}(\Phi))(p) = \Phi(\pi_1(p))$ for all $p \in M_n$. Let θ be a covector field in an *n*-dimensional manifold M_n . Then the transformation $p \to \theta_p, \theta_p$ being the value of θ at $p \in M_n$, determines a cross-section β_{θ} of the semi-cotangent bundle. Thus if $\sigma : B_m \to T^*(B_m)$ is a cross-section of

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 $(T^*(B_m), \tilde{\pi}, B_m)$, such that $\tilde{\pi} \circ \sigma = I_{(B_m)}$, an associated cross-section $\beta_{\theta} : M_n \to t^*(B_m)$ of semi-cotangent bundle $(t^*(B_m), \pi_2, M_n)$ defined by [[2], p. 217-218], [[8], p. 301]:

$$\beta_{\theta}\left(x^{a}, x^{\alpha}\right) = \left(x^{a}, x^{\alpha}, \sigma \circ \pi_{1}\left(x^{a}, x^{\alpha}\right)\right) = \left(x^{a}, x^{\alpha}, \sigma\left(x^{\alpha}\right)\right) = \left(x^{a}, x^{\alpha}, \theta_{\alpha}\left(x^{\beta}\right)\right).$$

2. Lifts of Vector Fields on a Cross-Section in the Semi-Cotangent Bundle

If the covector field θ has the local components $\theta_{\alpha}(x^{\beta})$, the cross-section $\beta_{\theta}(M_n)$ of $t^*(B_m)$ is locally expressed by

$$\begin{cases} x^{a} = x^{a}, \\ x^{\alpha} = x^{\alpha}, \\ x^{\overline{\alpha}} = p_{\alpha} = \theta_{\alpha} \left(x^{\beta} \right), \end{cases}$$
(2.1)

with respect to the coordinates $x^A = (x^a, x^{\alpha}, x^{\overline{\alpha}})$ on $t^*(B_m)$. x^a being considered as parameters. Taking the derivative with respect to x^b , we have k-local vector fields $B_{(b)}$ (k = 1, ..., n - m) with the components

$$B_{(b)} = \frac{\partial x^A}{\partial x^b} = \partial_b x^A = \begin{pmatrix} \partial_b x^a \\ \partial_b x^\alpha \\ \partial_b \theta_\alpha \end{pmatrix},$$

which are tangent to the cross-section $\beta_{\theta}(M_n)$. Thus $B_{(b)}$ has the components

$$B_{(b)}: \left(B_{(b)}^{A}\right) = \left(\begin{array}{c} \delta_{b}^{a} \\ 0 \\ 0 \end{array}\right)$$

with respect to the coordinates $(x^a, x^{\alpha}, x^{\overline{\alpha}})$ on $t^*(B_m)$. Where

$$\delta^a_b = A^a_b = \frac{\partial x^a}{\partial x^b}.$$

Let $\widetilde{X} \in \mathfrak{S}_0^1(M_n)$ be a projectable vector field [7] with projection $X = X^{\alpha}(x^{\alpha})\partial_{\alpha}$ i.e. $\widetilde{X} = \widetilde{X}^a(x^a, x^{\alpha})\partial_a + X^{\alpha}(x^{\alpha})\partial_{\alpha}$, we denote by BX the vector field with local components

$$BX: \left(B^{A}_{(b)}\widetilde{X}^{b}\right) = \left(\begin{array}{c}\delta^{a}_{b}\widetilde{X}^{b}\\0\\0\end{array}\right) = \left(\begin{array}{c}A^{a}_{b}\widetilde{X}^{b}\\0\\0\end{array}\right)$$
(2.2)

with respect to the coordinates $(x^a, x^{\alpha}, x^{\overline{\alpha}})$ on $t^*(B_m)$, which is defined globally along $\beta_{\theta}(M_n)$. Then a mapping

$$B: \mathfrak{S}^1_0(M_n) \to \mathfrak{S}^1_0(\beta_\theta(M_n))$$

is defined by (2.2). The mapping B is the differential of $\beta_{\theta} : M_n \to t^*(B_m)$ and so an isomorphism of $\mathfrak{S}^1_0(M_n)$ onto $\mathfrak{S}^1_0(\beta_{\theta}(M_n))$. Since a cross-section is locally expressed by

$$\begin{cases} x^{a} = const., \\ x^{\overline{\alpha}} = p_{\alpha} = const., \\ x^{\alpha} = x^{\alpha}, \end{cases}$$

 x^{α} being considered as parameters. Taking the derivative with respect to x^{β} , we have r-local vector fields $C_{(\beta)}$ (r = n - m + 1, ..., n) with the components

$$C_{(\beta)} = \frac{\partial x^A}{\partial x^\beta} = \partial_\beta x^A = \begin{pmatrix} \partial_\beta x^a \\ \partial_\beta x^\alpha \\ \partial_\beta \theta_\alpha \end{pmatrix},$$

which are tangent to the cross-section $\beta_{\theta}(M_n)$.

Thus $C_{(\beta)}$ has the components

$$C_{(\beta)}: \left(C^{A}_{(\beta)}\right) = \left(\begin{array}{c}A^{a}_{\beta}\\\delta^{\alpha}_{\beta}\\\partial_{\beta}\theta_{\alpha}\end{array}\right)$$

with respect to the coordinates $(x^a, x^{\alpha}, x^{\overline{\alpha}})$ on $t^*(B_m)$. Where

$$A^a_\beta = \frac{\partial x^a}{\partial x^\beta}, \quad \delta^\alpha_\beta = A^\alpha_\beta = \frac{\partial x^\alpha}{\partial x^\beta}.$$

Let $\widetilde{X} \in \mathfrak{S}_0^1(M_n)$ be a projectable vector field [7] with projection $X = X^{\alpha}(x^{\alpha})\partial_{\alpha}$ i.e. $\widetilde{X} = \widetilde{X}^a(x^a, x^{\alpha})\partial_a + X^{\alpha}(x^{\alpha})\partial_{\alpha}$. Then we denote by CX the vector field with local components

$$CX: \left(C^{A}_{(\beta)}X^{\beta}\right) = \left(\begin{array}{c}A^{a}_{\beta}X^{\beta}\\X^{\alpha}\\X^{\beta}\partial_{\beta}\theta_{\alpha}\end{array}\right)$$
(2.3)

with respect to the coordinates $(x^a, x^{\alpha}, x^{\overline{\alpha}})$ on $t^*(B_m)$, which is defined globally along $\beta_{\theta}(M_n)$. Then a mapping

$$C: \mathfrak{S}^1_0(M_n) \to \mathfrak{S}^1_0(\beta_\theta(M_n))$$

is defined by (2.3). The mapping C is the differential of $\beta_{\theta} : M_n \to t^*(B_m)$ and so an isomorphism of $\mathfrak{S}_0^1(M_n)$ onto $\mathfrak{S}_0^1(\beta_{\theta}(M_n))$.

Now, consider $\omega \in \mathfrak{S}_1^0(B_m)$ and projectable vector field $\widetilde{X} \in \mathfrak{S}_0^1(M_n)$, then ${}^{vv}\omega$ (vertical lift) and ${}^{cc}\widetilde{X}$ (complete lift) have respectively, components on the semi-cotangent bundle $t^*(B_m)$ [10]:

$${}^{vv}\omega = \begin{pmatrix} 0\\0\\\omega_{\alpha} \end{pmatrix}, \quad {}^{cc}\widetilde{X} = \begin{pmatrix} \widetilde{X}^{a}\\X^{\alpha}\\-p_{\varepsilon}(\partial_{\alpha}X^{\varepsilon}) \end{pmatrix}$$
(2.4)

with respect to the coordinates $(x^a, x^{\alpha}, x^{\overline{\alpha}})$.

On the other hand, the fibre is locally represented by

$$\begin{cases} x^{a} = const., \\ x^{\alpha} = const., \\ x^{\overline{\alpha}} = p_{\alpha} = p_{\alpha} \end{cases}$$

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 p_{α} being considered as parameters. Thus, by differentiating with respect to p_{α} , we easily see that the *l*-local vector fields $E_{(\overline{\beta})} =^{vv} (dx^{\beta}) (l = n + 1, ..., m)$ with components

$$E_{\left(\overline{\beta}\right)}:\left(E_{\left(\overline{\beta}\right)}^{A}\right)=\partial_{\overline{\beta}}x^{A}=\left(\begin{array}{c}\partial_{\overline{\beta}}x^{a}\\\partial_{\overline{\beta}}x^{\alpha}\\\partial_{\overline{\beta}}p_{\alpha}\end{array}\right)=\left(\begin{array}{c}0\\0\\\delta_{\alpha}^{\beta}\end{array}\right)$$

is tangent to the fibre, where

$$\delta^{\beta}_{\alpha} = A^{\beta}_{\alpha} = \frac{\partial x^{\beta}}{\partial x^{\alpha}}.$$

Let ω be an 1-form with local components ω_{α} on B_m , so that ω is a 1-form with local expression $\omega = \omega_{\alpha} dx^{\alpha}$. We denote by $E\omega$ the vector field with local components

$$E\omega: \left(E^{A}_{\left(\overline{\beta}\right)}\omega_{\beta}\right) = \left(\begin{array}{c}0\\0\\\omega_{\alpha}\end{array}\right),\tag{2.5}$$

which is tangent to the fibre. Then a mapping

$$E:\mathfrak{S}^0_1(B_m)\to\mathfrak{S}^1_0(t^*(B_m))$$

is defined by (2.5) and so an isomorphism of $\mathfrak{S}_1^0(B_m)$ in to $\mathfrak{S}_0^1(t^*(B_m))$.

According to (2.2) and (2.3), we define new projectable vector field HX by

$$BX + CX = H\hat{X}$$

with respect to the coordinates $(x^a, x^\alpha, x^{\overline{\alpha}})$ in $t^*(B_m)$, where

$$H\widetilde{X} = \begin{pmatrix} A_b^a \widetilde{X}^b \\ 0 \\ 0 \end{pmatrix} + \begin{pmatrix} A_\beta^a X^\beta \\ X^\alpha \\ X^\beta \partial_\beta \theta_\alpha \end{pmatrix} = \begin{pmatrix} A_b^a \widetilde{X}^b + A_\beta^a X^\beta \\ X^\alpha \\ X^\beta \partial_\beta \theta_\alpha \end{pmatrix} = \begin{pmatrix} \widetilde{X}^a \\ X^\alpha \\ X^\beta \partial_\beta \theta_\alpha \end{pmatrix}.$$
(2.6)

From (2.5) and (2.6), we obtain

Theorem 2.1. Let \widetilde{X} and \widetilde{Y} be projectable vector fields on M_n with projections X and Y on B_m , respectively. For the Lie product, we have

(i)
$$\begin{bmatrix} H\widetilde{X}, H\widetilde{Y} \end{bmatrix} = H\widetilde{[X, Y]},$$

(ii) $[E\psi, E\omega] = 0$
for any $\psi, \omega \in \Im_1^0(B_m).$

Proof. (i) If \widetilde{X} and \widetilde{Y} are projectable vector field on M_n and $\begin{pmatrix} [H\widetilde{X}, H\widetilde{Y}]^{"}\\ [H\widetilde{X}, H\widetilde{Y}]^{\beta}\\ [H\widetilde{X}, H\widetilde{Y}]^{\beta} \end{pmatrix}$

are the components of $\left[H\widetilde{X}, H\widetilde{Y}\right]$ with respect to the coordinates $(x^b, x^\beta, x^{\overline{\beta}})$ on

 $t^*(B_m)$, then we have

$$\left[H\widetilde{X}, H\widetilde{Y}\right]^{J} = \left(H\widetilde{X}\right)^{I} \partial_{I} (H\widetilde{Y})^{J} - (H\widetilde{Y})^{I} \partial_{I} (H\widetilde{X})^{J}.$$

Firstly, if J = b, we have

$$\begin{split} \left[H\widetilde{X}, H\widetilde{Y} \right]^{b} &= \left(H\widetilde{X} \right)^{I} \partial_{I} (H\widetilde{Y})^{b} - (H\widetilde{Y})^{I} \partial_{I} (H\widetilde{X})^{b} \\ &= \left(H\widetilde{X} \right)^{a} \partial_{a} (H\widetilde{Y})^{b} + \left(H\widetilde{X} \right)^{\alpha} \partial_{\alpha} (H\widetilde{Y})^{b} + \left(H\widetilde{X} \right)^{\overline{\alpha}} \partial_{\overline{\alpha}} (H\widetilde{Y})^{b} \\ &- (H\widetilde{Y})^{a} \partial_{a} (H\widetilde{X})^{b} - (H\widetilde{Y})^{\alpha} \partial_{\alpha} (H\widetilde{X})^{b} - (H\widetilde{Y})^{\overline{\alpha}} \partial_{\overline{\alpha}} (H\widetilde{X})^{b} \\ &= \widetilde{X}^{a} \partial_{a} \widetilde{Y}^{b} + X^{\alpha} \partial_{\alpha} \widetilde{Y}^{b} + X^{\beta} \partial_{\beta} \theta_{\alpha} \partial_{\overline{\alpha}} \widetilde{Y}^{b} \\ &- \widetilde{Y}^{a} \partial_{a} \widetilde{X}^{b} - Y^{\alpha} \partial_{\alpha} \widetilde{X}^{b} - Y^{\beta} \partial_{\beta} \theta_{\alpha} \partial_{\overline{\alpha}} \widetilde{X}^{b} \\ &= X^{\alpha} \partial_{\alpha} \widetilde{Y}^{b} - Y^{\alpha} \partial_{\alpha} \widetilde{X}^{b} \\ &= \widetilde{[X, Y]}^{b} \end{split}$$

by virtue of (2.6). Secondly, if $J = \beta$, we have

$$\begin{split} \left[H\widetilde{X}, H\widetilde{Y} \right]^{\beta} &= \left(H\widetilde{X} \right)^{I} \partial_{I} (H\widetilde{Y})^{\beta} - (H\widetilde{Y})^{I} \partial_{I} (H\widetilde{X})^{\beta} \\ &= \left(H\widetilde{X} \right)^{a} \partial_{a} (H\widetilde{Y})^{\beta} + \left(H\widetilde{X} \right)^{\alpha} \partial_{\alpha} (H\widetilde{Y})^{\beta} + \left(H\widetilde{X} \right)^{\overline{\alpha}} \partial_{\overline{\alpha}} (H\widetilde{Y})^{\beta} \\ &- (H\widetilde{Y})^{a} \partial_{a} (H\widetilde{X})^{\beta} - (H\widetilde{Y})^{\alpha} \partial_{\alpha} (H\widetilde{X})^{\beta} - (H\widetilde{Y})^{\overline{\alpha}} \partial_{\overline{\alpha}} (H\widetilde{X})^{\beta} \\ &= \widetilde{X}^{a} \partial_{a} Y^{\beta} + X^{\alpha} \partial_{\alpha} Y^{\beta} + X^{\beta} \partial_{\beta} \theta_{\alpha} \partial_{\overline{\alpha}} Y^{\beta} \\ &- \widetilde{Y}^{a} \partial_{a} X^{\beta} - Y^{\alpha} \partial_{\alpha} X^{\beta} - Y^{\beta} \partial_{\beta} \theta_{\alpha} \partial_{\overline{\alpha}} X^{\beta} \\ &= X^{\alpha} \partial_{\alpha} Y^{\beta} - Y^{\alpha} \partial_{\alpha} X^{\beta} \\ &= [X, Y]^{\beta} \end{split}$$

by virtue of (2.6). Thirdly, if $J = \overline{\beta}$ then we have

$$\begin{split} \left[H\widetilde{X}, H\widetilde{Y} \right]^{\beta} &= \left(H\widetilde{X} \right)^{I} \partial_{I} (H\widetilde{Y})^{\overline{\beta}} - (H\widetilde{Y})^{I} \partial_{I} (H\widetilde{X})^{\overline{\beta}} \\ &= \left(H\widetilde{X} \right)^{a} \partial_{a} (H\widetilde{Y})^{\overline{\beta}} + \left(H\widetilde{X} \right)^{\alpha} \partial_{\alpha} (H\widetilde{Y})^{\overline{\beta}} + \left(H\widetilde{X} \right)^{\overline{\alpha}} \partial_{\overline{\alpha}} (H\widetilde{Y})^{\overline{\beta}} \\ &- (H\widetilde{Y})^{a} \partial_{a} (H\widetilde{X})^{\overline{\beta}} - (H\widetilde{Y})^{\alpha} \partial_{\alpha} (H\widetilde{X})^{\overline{\beta}} - (H\widetilde{Y})^{\overline{\alpha}} \partial_{\overline{\alpha}} (H\widetilde{X})^{\overline{\beta}} \\ &= \widetilde{X}^{a} \partial_{a} Y^{\gamma} \partial_{\gamma} \theta_{\beta} + X^{\alpha} \partial_{\alpha} Y^{\gamma} \partial_{\gamma} \theta_{\beta} + X^{\beta} \partial_{\beta} \theta_{\alpha} \partial_{\overline{\alpha}} Y^{\gamma} \partial_{\gamma} \theta_{\beta} \\ &- \widetilde{Y}^{a} \partial_{a} X^{\gamma} \partial_{\gamma} \theta_{\beta} - Y^{\alpha} \partial_{\alpha} X^{\gamma} \partial_{\gamma} \theta_{\beta} - Y^{\beta} \partial_{\beta} \theta_{\alpha} \partial_{\overline{\alpha}} X^{\gamma} \partial_{\gamma} \theta_{\beta} \\ &= X^{\alpha} \partial_{\alpha} Y^{\gamma} \partial_{\gamma} \theta_{\beta} - Y^{\alpha} \partial_{\alpha} X^{\gamma} \partial_{\gamma} \theta_{\beta} \\ &= (X^{\alpha} \partial_{\alpha} Y^{\gamma} - Y^{\alpha} \partial_{\alpha} X^{\gamma}) \partial_{\gamma} \theta_{\beta} \\ &= [X, Y]^{\gamma} \partial_{\gamma} \theta_{\beta} \end{split}$$

by virtue of (2.6). On the other hand, we know that H[X, Y] has the components

$$H\widetilde{[X,Y]} = \begin{pmatrix} \widetilde{[X,Y]}^{b} \\ [X,Y]^{\beta} \\ [X,Y]^{\gamma} \partial_{\gamma} \theta_{\beta} \end{pmatrix}$$

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with respect to the coordinates $(x^b, x^{\beta}, x^{\overline{\beta}})$ on $t^*(B_m)$. Thus, we have $\left[H\widetilde{X}, H\widetilde{Y}\right] = H\widetilde{[X,Y]}$.

(*ii*) If
$$\psi, \omega \in \mathfrak{S}_1^0(B_m)$$
 and $\begin{pmatrix} [E\psi, E\omega]^b \\ [E\psi, E\omega]^\beta \\ [E\psi, E\omega]^{\overline{\beta}} \end{pmatrix}$ are the components of $[E\psi, E\omega]$

with respect to the coordinates (x^b, x^β, x^β) on $t^*(B_m)$, then we have

$$\begin{split} [\psi,\omega]^J &= \psi^I \partial_I \omega^J - \omega^I \partial_I \psi^J \\ &= \psi^a \partial_a \omega^J + \psi^\alpha \partial_\alpha \omega^J + \psi^{\overline{\alpha}} \partial_{\overline{\alpha}} \omega^J - \omega^a \partial_a \psi^J - \omega^\alpha \partial_\alpha \psi^J - \omega^{\overline{\alpha}} \partial_{\overline{\alpha}} \psi^J \\ &= \psi_\alpha \partial_{\overline{\alpha}} \omega^J - \omega_\alpha \partial_{\overline{\alpha}} \psi^J. \end{split}$$

Firstly, if J = b, we have

$$\begin{aligned} [\psi, \omega]^b &= \psi_\alpha \partial_{\overline{\alpha}} \omega^b - \omega_\alpha \partial_{\overline{\alpha}} \psi^b \\ &= 0 \end{aligned}$$

by virtue of (2.5). Secondly, if $J = \beta$, we have

$$\begin{aligned} [\psi, \omega]^{\beta} &= \psi_{\alpha} \partial_{\overline{\alpha}} \omega^{\beta} - \omega_{\alpha} \partial_{\overline{\alpha}} \psi^{\beta} \\ &= 0 \end{aligned}$$

by virtue of (2.5). Thirdly, if $J = \overline{\beta}$. Then we have

$$\begin{split} [\psi, \omega]^{\overline{\beta}} &= \psi_{\alpha} \partial_{\overline{\alpha}} \omega^{\overline{\beta}} - \omega_{\alpha} \partial_{\overline{\alpha}} \psi^{\overline{\beta}} \\ &= \psi_{\alpha} \partial_{\overline{\alpha}} \omega_{\beta} - \omega_{\alpha} \partial_{\overline{\alpha}} \psi_{\beta} \\ &= 0 \end{split}$$

by virtue of (2.5). Thus, we have $[E\psi, E\omega] = 0$.

We consider in $\pi^{-1}(U)$ n+m local vector fields $B_{(b)}, C_{(\beta)}$ and $E_{(\overline{\beta})}$ along $\beta_{\theta}(M_n)$, which are respectively represented by

$$B_{(b)} = B \frac{\partial}{\partial x^b}, \quad C_{(\beta)} = C \frac{\partial}{\partial x^\beta}, \quad E_{\left(\overline{\beta}\right)} = E dx^\beta.$$

Theorem 2.2. Let \widetilde{X} be a projectable vector field on M_n with projection X on B_m . We have along $\beta_{\theta}(M_n)$ the formulas

(i)
$${}^{cc}\widetilde{X} = H\widetilde{X} + E(-L_X\theta),$$

(ii) ${}^{vv}\omega = E\omega$
(2.7)

for any $\omega \in \mathfrak{S}_1^0(B_m)$, where $L_X \theta$ denotes the Lie derivative of θ with respect to X.

Proof. (i) Using (2.4), (2.5) and (2.6), we have

$$\begin{split} H\widetilde{X} + E\left(-L_{X}\theta\right) &= \begin{pmatrix} \widetilde{X}^{a} \\ X^{\alpha} \\ X^{\beta}\partial_{\beta}\theta_{\alpha} \end{pmatrix} + \begin{pmatrix} 0 \\ 0 \\ -X^{\beta}\partial_{\beta}\theta_{\alpha} - \theta_{\beta}\partial_{\alpha}X^{\beta} \end{pmatrix} \\ &= \begin{pmatrix} \widetilde{X}^{a} \\ X^{\alpha} \\ -\theta_{\beta}\partial_{\alpha}X^{\beta} \end{pmatrix} \\ &= {}^{cc}\widetilde{X}. \end{split}$$

Thus, we have Theorem 2.2.

(ii) This immediately follows from (2.4).

On the other hand, on putting $C_{(\overline{\beta})} = E_{(\overline{\beta})}$, we write the adapted frame of $\beta_{\theta}(M_n)$ as $\{B_{(b)}, C_{(\beta)}, C_{(\overline{\beta})}\}$. The adapted frame $\{B_{(b)}, C_{(\beta)}, C_{(\overline{\beta})}\}$ of $\beta_{\theta}(M_n)$ is given by the matrix

$$\widetilde{A} = \left(\widetilde{A}_B^A\right) = \begin{pmatrix} \delta_b^a & A_\beta^a & 0\\ 0 & \delta_\beta^\alpha & 0\\ 0 & \partial_\beta \theta_\alpha & \delta_\alpha^\beta \end{pmatrix}.$$
(2.8)

Where

$$\delta^a_b = A^a_b = \frac{\partial x^a}{\partial x^b}, \quad \delta^\alpha_\beta = A^\alpha_\beta = \frac{\partial x^\alpha}{\partial x^\beta}, \quad \delta^\beta_\alpha = A^\beta_\alpha = \frac{\partial x^\beta}{\partial x^\alpha}, \quad A^a_\beta = \frac{\partial x^a}{\partial x^\beta}.$$

Since the matrix \widetilde{A} in (2.8) is non-singular, it has the inverse. Denoting this inverse by $\left(\widetilde{A}\right)^{-1}$, we have

$$\left(\widetilde{A}\right)^{-1} = \left(\widetilde{A}_C^B\right)^{-1} = \begin{pmatrix} \delta_c^b & -A_\theta^b & 0\\ 0 & \delta_\theta^\beta & 0\\ 0 & -\partial_\theta\theta_\beta & \delta_\beta^\theta \end{pmatrix}, \qquad (2.9)$$

since $\widetilde{A}\left(\widetilde{A}\right)^{-1} = \widetilde{A}_B^A\left(\widetilde{A}_C^B\right)^{-1} = \delta_C^A = \widetilde{I}$. Where $A = (a, \alpha, \overline{\alpha}), B = (b, \beta, \overline{\beta}), C = (c, \theta, \overline{\theta})$.

Proof. In fact, from (2.8) and (2.9), we easily see that

$$\begin{split} \widetilde{A}\left(\widetilde{A}\right)^{-1} &= \widetilde{A}^{A}_{B}\left(\widetilde{A}^{B}_{C}\right)^{-1} \\ &= \begin{pmatrix} \delta^{a}_{b} & A^{a}_{\beta} & 0\\ 0 & \delta^{\alpha}_{\beta} & 0\\ 0 & \partial_{\beta}\theta_{\alpha} & \delta^{\beta}_{\alpha} \end{pmatrix} \begin{pmatrix} \delta^{b}_{c} & -A^{b}_{\theta} & 0\\ 0 & \delta^{\beta}_{\theta} & 0\\ 0 & -\partial_{\theta}\theta_{\beta} & \delta^{\theta}_{\beta} \end{pmatrix} \\ &= \begin{pmatrix} \delta^{a}_{c} & -A^{a}_{\theta} + A^{a}_{\theta} & 0\\ 0 & \delta^{\alpha}_{\theta} & 0\\ 0 & \partial_{\theta}\theta_{\alpha} - \partial_{\theta}\theta_{\alpha} & \delta^{\theta}_{\alpha} \end{pmatrix} = \begin{pmatrix} \delta^{a}_{c} & 0 & 0\\ 0 & \delta^{\alpha}_{\theta} & 0\\ 0 & 0 & \delta^{\theta}_{\alpha} \end{pmatrix} = \delta^{A}_{C} = \widetilde{I}. \end{split}$$

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Then we see from (2.7) that the complete lift ${}^{cc}\widetilde{X}$ of a projectable vector field [7] with projection $X = X^{\alpha}(x^{\alpha})\partial_{\alpha}$ on M_n has along $\beta_{\theta}(M_n)$ components of the form

$${}^{cc}\widetilde{X}:\left(\begin{array}{c}\widetilde{X}^{a}\\X^{\alpha}\\-L_{X}\theta_{\alpha}\end{array}\right) \tag{2.10}$$

with respect to the adapted frame $\left\{B_{(b)}, C_{(\beta)}, C_{(\overline{\beta})}\right\}$.

BX, CX and $E\omega$ also have the components:

$$BX = \begin{pmatrix} \tilde{X}^{a} \\ 0 \\ 0 \end{pmatrix}, \quad CX = \begin{pmatrix} 0 \\ X^{\alpha} \\ 0 \end{pmatrix}, \quad E\omega = \begin{pmatrix} 0 \\ 0 \\ \omega_{\alpha} \end{pmatrix}$$
(2.11)

respectively, with respect to the adapted frame $\{B_{(b)}, C_{(\beta)}, C_{(\overline{\beta})}\}$ of the cross-section $\beta_{\theta}(M_n)$ determined by a 1-form θ in M_n .

A vector field ${}^{cc}\widetilde{X}$ on a differentiable map $\Omega : M_n \to t^*(B_m)$ is a mapping ${}^{cc}\widetilde{X} : M_n \to T(t^*(B_m))$ such that $\pi_4 \circ {}^{cc}\widetilde{X} = \Omega$, where π_4 is the projection $T(t^*(B_m)) \to t^*(B_m)$. Thus ${}^{cc}\widetilde{X}$ assigns to each point $(x^a, x^\alpha) = p \in M_n$ a tangent vector to $t^*(B_m)$ at $\Omega(p)$. ${}^{cc}\widetilde{X}$ is differentiable as a mapping $M_n \to T(t^*(B_m))$ if and only if $f \in \mathfrak{S}(t^*(B_m))$ implies, ${}^{cc}\widetilde{X}f \in \mathfrak{S}(M_n)$, where ${}^{(cc}\widetilde{X}f)(p) = {}^{cc}\widetilde{X}(p)f$ for all $p \in M_n$ [4].

Thus, from (2.10), we have

Theorem 2.3. The complete lift ${}^{cc}\widetilde{X}$ of a projectable vector field \widetilde{X} on M_n to $t^*(B_m)$ is tangent to the cross-section $\beta_{\theta}(M_n)$ determined by a 1-form θ in M_n if and only if the Lie derivative of θ with respect to X vanishes in M_n , i.e., if and only if $L_X \theta = 0$.

3. Complete Lift of Tensor Fields of Type (1,1) on a

Cross-Section in Semi-Cotangent Bundle

Let $\widetilde{F} \in \mathfrak{S}_1^1(M_n)$ be a projectable affinor field [7] with projection $F = F_\beta^\alpha(x^\alpha)\partial_\alpha \otimes dx^\beta$, i.e. \widetilde{F} has the components

$$\widetilde{F} = (\widetilde{F}_j^i) = \left(\begin{array}{cc} \widetilde{F}_b^a(x^a, x^\alpha) & \widetilde{F}_\beta^a(x^a, x^\alpha) \\ 0 & F_\beta^\alpha(x^\alpha) \end{array}\right)$$

with respect to the coordinates (x^a, x^{α}) . Then the semi-cotangent bundle $t^*(B_m)$ admits the complete lift $c^c \tilde{F}$ of \tilde{F} with components [10]:

$${}^{cc}\widetilde{F} = ({}^{cc}\widetilde{F}_J^I) = \begin{pmatrix} \widetilde{F}_b^a & \widetilde{F}_\beta^a & 0\\ 0 & F_\beta^\alpha & 0\\ 0 & p_\sigma(\partial_\beta F_\alpha^\sigma - \partial_\alpha F_\beta^\sigma) & F_\alpha^\beta \end{pmatrix}$$
(3.1)

with respect to the coordinates $(x^a, x^{\alpha}, x^{\overline{\alpha}})$ on $t^*(B_m)$. Then ${}^{cc}\widetilde{F}$ has the components \widetilde{F}_B^A given by

$${}^{cc}\widetilde{F} = ({}^{cc}\widetilde{F}_B^A) = \begin{pmatrix} \widetilde{F}_b^a & \widetilde{F}_\beta^a & 0\\ 0 & F_\beta^\alpha & 0\\ 0 & \phi_F\theta & F_\alpha^\beta \end{pmatrix}$$
(3.2)

with respect to the adapted frame $\left\{B_{(b)}, C_{(\beta)}, C_{(\overline{\beta})}\right\}$ of the cross-section $\beta_{\theta}(M_n)$ determined by a 1-form θ in M_n . Where $A = (a, \alpha, \overline{\alpha}), B = (b, \beta, \overline{\beta})$. Also, the component ${}^{cc}\widetilde{F}^{\alpha}_{\beta}$ of ${}^{cc}\widetilde{F}^{A}_{B}$ is defined as Tachibana operator $\phi_F \theta$ of F, i.e.,

$${}^{cc}\widetilde{F}^{\overline{\alpha}}_{\beta} = \phi_F \theta = (\partial_{\beta}F^{\sigma}_{\alpha} - \partial_{\alpha}F^{\sigma}_{\beta})\theta_{\sigma} - F^{\gamma}_{\beta}\partial_{\gamma}\theta_{\alpha} + F^{\gamma}_{\alpha}\partial_{\beta}\theta_{\gamma}.$$

Proof. Let $F \in \mathfrak{S}_1^1(M_n)$. Then we have by (2.8), (2.9) and (3.1):

$$\begin{split} \tilde{F} &= \left(\tilde{A}^B_A\right)^{-1} \left(\begin{smallmatrix} {}^{cc} \tilde{F}^A_C \right) \left(\tilde{A}^C_D \right) \\ &= \left(\begin{smallmatrix} \delta^b_a & -A^b_\alpha & 0 \\ 0 & \delta^\beta_\alpha & 0 \\ 0 & -\partial_\alpha \theta_\beta & \delta^\alpha_\beta \end{smallmatrix} \right) \left(\begin{smallmatrix} \tilde{F}^a_c & \tilde{F}^a_\gamma & 0 \\ 0 & F^\alpha_\gamma & 0 \\ 0 & \theta_\sigma (\partial_\gamma F^\sigma_\alpha - \partial_\alpha F^\sigma_\gamma) & F^\alpha_\alpha \end{smallmatrix} \right) \left(\begin{smallmatrix} \delta^c_d & A^c_\psi & 0 \\ 0 & \delta^\psi_\psi & 0 \\ 0 & \partial_\psi \theta_\gamma & \delta^\psi_\gamma \end{smallmatrix} \right) \\ &= \left(\begin{smallmatrix} \tilde{F}^b_c & 0 & 0 \\ 0 & F^\beta_\gamma & 0 \\ 0 & -F^\alpha_\gamma \partial_\alpha \theta_\beta + \theta_\sigma \partial_\gamma F^\sigma_\beta - \theta_\sigma \partial_\beta F^\sigma_\gamma & F^\alpha_\beta \end{smallmatrix} \right) \left(\begin{smallmatrix} \delta^c_d & A^c_\psi & 0 \\ 0 & \delta^\psi_\psi & 0 \\ 0 & \partial_\psi \theta_\gamma & \delta^\psi_\gamma \end{smallmatrix} \right) \\ &= \left(\begin{smallmatrix} \tilde{F}^b_d & A^c_\psi \tilde{F}^c_c & 0 \\ 0 & F^\beta_\psi & 0 \\ 0 & -F^\alpha_\psi \partial_\alpha \theta_\beta + \theta_\sigma \partial_\psi F^\sigma_\beta - \theta_\sigma \partial_\beta F^\sigma_\psi + F^\alpha_\beta \partial_\psi \theta_\gamma & F^\psi_\beta \end{smallmatrix} \right) \\ &= \left(\begin{smallmatrix} \tilde{F}^b_d & \tilde{F}^b_\psi & 0 \\ 0 & F^\beta_\psi & 0 \\ 0 & -F^\alpha_\psi \partial_\alpha \theta_\beta + \theta_\sigma \partial_\psi F^\sigma_\beta - \theta_\sigma \partial_\beta F^\sigma_\psi + F^\alpha_\beta \partial_\psi \theta_\gamma & F^\psi_\beta \end{smallmatrix} \right) \\ &= \left(\begin{smallmatrix} \tilde{F}^b_d & \tilde{F}^b_\psi & 0 \\ 0 & F^\beta_\psi & 0 \\ 0 & \phi_F \theta & F^\psi_\beta \end{smallmatrix} \right) \\ &= \left(\begin{smallmatrix} \tilde{F}^b_d & \tilde{F}^b_\psi & 0 \\ 0 & \phi_F \theta & F^\psi_\beta \end{smallmatrix} \right) \\ &= \left(\begin{smallmatrix} c^c \tilde{F}^B_D \right), \end{split}$$

where $A = (a, \alpha, \overline{\alpha}), B = (b, \beta, \overline{\beta}), C = (c, \gamma, \overline{\gamma}), D = (d, \psi, \overline{\psi}).$

Theorem 3.1. Let \widetilde{F} and \widetilde{X} be projectable affinor and vector fields on M_n with projections F and X on B_m , respectively, and $\omega \in \mathfrak{S}^0_1(B_m)$. Then we have along $\beta_{\theta}(M_n)$

- $(i)^{(M_R)} cc \widetilde{F} (BX + CX) = B (FX) + C (FX) + E (P_X),$
- $(ii) \quad {}^{cc}\widetilde{F}(E\omega) = E(\omega \circ F),$

where $P \in \mathfrak{S}_2^0(B_m)$ with local components

$$P_{\beta\alpha} = \phi_F \theta = (\partial_\beta F^\sigma_\alpha - \partial_\alpha F^\sigma_\beta) \theta_\sigma - F^\gamma_\beta \partial_\gamma \theta_\alpha + F^\gamma_\alpha \partial_\beta \theta_\gamma,$$

 θ_{β} being the local components of θ , and $P_X \in \mathfrak{S}^0_1(B_m)$ defined by $P_X(Y) = P(X,Y)$, for $Y \in \mathfrak{S}^0_0(M_n)$.

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Proof. (i) If \widetilde{F} and \widetilde{X} are projectable affinor and vector fields on M_n with projections F and X on B_m , respectively, then by (2.11) and (3.2), we have

$$\begin{split} ^{cc}\widetilde{F}\left(BX+CX\right) &= \begin{pmatrix} F_{b}^{a} & F_{\beta}^{a} & 0\\ 0 & F_{\beta}^{\alpha} & 0\\ 0 & \phi_{F}\theta & F_{\alpha}^{\beta} \end{pmatrix} \begin{pmatrix} \widetilde{X}^{b} \\ X^{\beta} \\ 0 \end{pmatrix} \\ &= \begin{pmatrix} \widetilde{F}_{b}^{a}\widetilde{X}^{b} + \widetilde{F}_{\beta}^{a}X^{\beta} \\ F_{\beta}^{\alpha}X^{\beta} \\ X^{\beta}\partial_{\beta}F_{\alpha}^{\sigma}\theta_{\sigma} - X^{\beta}\partial_{\alpha}F_{\beta}^{\sigma}\theta_{\sigma} - F_{\beta}^{\gamma}X^{\beta}\partial_{\gamma}\theta_{\alpha} + F_{\alpha}^{\gamma}X^{\beta}\partial_{\beta}\theta_{\gamma} \end{pmatrix} \\ &= \begin{pmatrix} \widetilde{(FX)}^{a} \\ (FX)^{\alpha} \\ X^{\beta}\partial_{\beta}F_{\alpha}^{\sigma}\theta_{\sigma} - X^{\beta}\partial_{\alpha}F_{\beta}^{\sigma}\theta_{\sigma} - F_{\beta}^{\gamma}X^{\beta}\partial_{\gamma}\theta_{\alpha} + F_{\alpha}^{\gamma}X^{\beta}\partial_{\beta}\theta_{\gamma} \end{pmatrix} \\ &= \begin{pmatrix} \widetilde{(FX)}^{b} \\ 0 \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ (FX)^{\beta} \\ 0 \end{pmatrix} \\ &+ \begin{pmatrix} 0 \\ 0 \\ X^{\beta}\partial_{\beta}F_{\alpha}^{\sigma}\theta_{\sigma} - X^{\beta}\partial_{\alpha}F_{\beta}^{\sigma}\theta_{\sigma} - F_{\beta}^{\gamma}X^{\beta}\partial_{\gamma}\theta_{\alpha} + F_{\alpha}^{\gamma}X^{\beta}\partial_{\beta}\theta_{\gamma} \end{pmatrix} \\ &= B\left(FX\right) + C\left(FX\right) + E\left(P_{X}\right). \end{split}$$

Thus, we have

$$^{cc}\widetilde{F}\left(BX+CX\right)=B\left(FX\right)+C\left(FX\right)+E\left(P_{X}\right).$$

(ii) If $\omega \in \mathfrak{S}_1^0(B_m)$, \widetilde{F} is a projectable affinor fields on M_n with projection $F \in \mathfrak{S}_1^1(B_m)$, then by (2.11) and (3.2), we have

Thus, we have (ii) of Theorem 3.1.

On the other hand, for an arbitrary symmetric affine connection ∇ in B_m , we have

$$P_{\beta\alpha} = (\nabla_{\beta}F_{\alpha}^{\sigma} - \nabla_{\alpha}F_{\beta}^{\sigma})\theta_{\sigma} - F_{\beta}^{\gamma}\nabla_{\gamma}\theta_{\alpha} + F_{\alpha}^{\gamma}\nabla_{\beta}\theta_{\gamma}.$$

When ${}^{cc}\widetilde{F}(BX + CX)$ is always tangent to $\beta_{\theta}(M_n)$ for any projectable vector field $\widetilde{X} \in \mathfrak{S}_0^1(M_n)$, ${}^{cc}\widetilde{F}$ is said to leave the cross-section $\beta_{\theta}(M_n)$ invariant.

Thus we have

Theorem 3.2. The complete lift ${}^{cc}\widetilde{F}$ of an element of $\widetilde{F} \in \mathfrak{S}_1^1(M_n)$ leaves the cross-section $\beta_{\theta}(M_n)$ invariant if and only if

 $(\partial_{\beta}F^{\sigma}_{\alpha} - \partial_{\alpha}F^{\sigma}_{\beta})\theta_{\sigma} - F^{\gamma}_{\beta}\partial_{\gamma}\theta_{\alpha} + F^{\gamma}_{\alpha}\partial_{\beta}\theta_{\gamma} = 0 \ (i.e.\phi_{F}\theta = 0),$

where F^{α}_{β} and θ_{β} are the local components of F and θ respectively.

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